

VARIATIONAL SOLUTION OF THIRD
BOUNDARY-VALUE PROBLEM OF
HEAT CONDUCTION

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It is shown that the Ainola variational principle can be used to solve the third boundary-value problem of heat conduction.

L. Ya. Ainola has given a variational principle [1] for solution of the first and second heat-conduction boundary-value problems. Here we shall show that this principle can be used to solve the third linear one-dimensional boundary-value problem which is formulated as

$$\frac{1}{x^{m-1}} \frac{\partial}{\partial x} \left[\lambda(x) x^{m-1} \frac{\partial T(x, \tau)}{\partial x} \right] = c\rho(x) \frac{\partial T(x, \tau)}{\partial \tau} - q_v(x, \tau), \quad (1)$$

$$a < x < b, \quad \tau > 0$$

($m = 1, 2, 3$ for a plate, cylinder, and sphere, respectively) under the initial condition

$$T(x, 0) = \varphi(x), \quad a < x < b \quad (2)$$

and the boundary condition

$$\lambda(a) \frac{\partial T(a, \tau)}{\partial x} + \alpha_1 [T_{a_1}(\tau) - T(a, \tau)] = 0, \quad \tau > 0, \quad (3)$$

$$-\lambda(b) \frac{\partial T(b, \tau)}{\partial x} + \alpha_2 [T_{a_2}(\tau) - T(b, \tau)] = 0, \quad \tau > 0. \quad (4)$$

Thus we consider the variation of the temperature T only in the x direction and during the time τ when the thermal conductivity λ and the bulk specific heat c_p depend on x and the body contains a bulk heat-evolving source of power $q_v(x, \tau)$. The convective heat-transfer coefficients α_1 and α_2 are assumed to be constant, and the initial temperature distribution $T(x, 0) = \varphi(x)$ and the variation of the temperatures in the ambient medium $T_{a_1}(\tau)$ and $T_{a_2}(\tau)$ are assumed to be continuous functions that together with their first derivatives satisfy the congruence conditions

$$\lambda(a) \varphi'(a) + \alpha_1 [T_{a_1}(0) - \varphi(a)] = 0, \quad (5)$$

$$-\lambda(b) \varphi'(b) + \alpha_2 [T_{a_2}(0) - \varphi(b)] = 0. \quad (6)$$

The lack of such congruence in the formulation of the problem is easily remedied by the computational method described below.

We introduce the new unknown function $u(x, \tau)$ such that

$$T(x, \tau) = u(x, \tau) + \varphi(x) + [T_{a_1}(\tau) - T_{a_1}(0)] \frac{(b-x)^2 (2x+b-3a)}{(b-a)^3} + [T_{a_2}(\tau) - T_{a_2}(0)] \frac{(x-a)^2 (3b-a-2x)}{(b-a)^3}, \quad (7)$$

and then reduce problem (1)-(4) to homogeneous initial and boundary conditions:

$$\frac{1}{x^{m-1}} \frac{\partial}{\partial x} \left[\lambda(x) x^{m-1} \frac{\partial u(x, \tau)}{\partial x} \right] - c\rho(x) \frac{\partial u(x, \tau)}{\partial \tau} - f(x, \tau) = 0, \quad (1')$$

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$$a < x < b, \tau > 0, m = 1, 2, 3,$$

$$u(x, 0) = 0, a < x < b, \quad (2')$$

$$-\lambda(a) \frac{\partial u(a, \tau)}{\partial x} + \alpha_1 u(a, \tau) = 0, \tau > 0, \quad (3')$$

$$\lambda(b) \frac{\partial u(b, \tau)}{\partial x} + \alpha_2 u(b, \tau) = 0, \tau > 0, \quad (4')$$

where

$$\begin{aligned} f(x, \tau) = & \frac{c\rho(x)}{(b-a)^3} [T_{a_1}'(\tau)(b-x)^2(2x+b-3a) + T_{a_2}'(\tau)(x-a)^2 \times \\ & \times (3b-a-2x)] - q_v(x, \tau) - \frac{1}{x^{m-1}} \frac{\partial}{\partial x} \{ |x^{m-1} \lambda(x) \{\varphi'(x) + \\ & + \frac{6(b-a)(x-a)}{(b-a)^3} [T_{a_2}(\tau) - T_{a_2}(0) - T_{a_1}(\tau) + T_{a_1}(0)] \} \}. \end{aligned} \quad (8)$$

In accordance with [1] we set up the functional in u for the finite temporal $[0, t]$ and spatial $[a, b]$ intervals:

$$\begin{aligned} J(u) = & \int_0^t \int_a^b \left\{ \frac{1}{x^{m-1}} \frac{\partial}{\partial x} \left[\lambda(x) x^{m-1} \frac{\partial u(x, \tau)}{\partial x} \right] - c\rho(x) \frac{\partial u(x, \tau)}{\partial \tau} - \right. \\ & \left. - 2f(x, \tau) |x^{m-1} u(x, t-\tau) \right\} dx d\tau. \end{aligned} \quad (9)$$

Integrating the first term on the right side of (9) by parts with respect to x and using (3') and (4') we obtain

$$\begin{aligned} J(u) = & - \int_0^t \left\{ \int_a^b \left[\lambda(x) \frac{\partial u(x, \tau)}{\partial x} \frac{\partial u(x, t-\tau)}{\partial x} + \right. \right. \\ & \left. \left. + c\rho(x) \frac{\partial u(x, \tau)}{\partial \tau} u(x, t-\tau) + 2f(x, \tau) u(x, t-\tau) \right] x^{m-1} dx + \right. \\ & \left. + 2[\alpha_2 b^{m-1} u(b, \tau) u(b, t-\tau) + \alpha_1 a^{m-1} u(a, \tau) u(a, t-\tau)] \right\} d\tau. \end{aligned} \quad (9')$$

We represent the variation of $u(x, \tau)$ by $\xi(x, \tau)$ and make use of the convolution-symmetry property to obtain the following form of variation for the given functional:

$$\begin{aligned} \delta J(u) = & - \int_0^t \left\{ \int_a^b 2\lambda(x) \frac{\partial u(x, \tau)}{\partial x} \frac{\partial \xi(x, t-\tau)}{\partial x} + c\rho(x) \times \right. \\ & \times \left[u(x, \tau) \frac{\partial \xi(x, t-\tau)}{\partial \tau} + \frac{\partial u(x, \tau)}{\partial \tau} \xi(x, t-\tau) \right] + \\ & \left. + 2f(x, \tau) \xi(x, t-\tau) \right\} x^{m-1} dx + 2[\alpha_2 b^{m-1} u(b, \tau) \xi(b, t-\tau) + \\ & + \alpha_1 a^{m-1} u(a, \tau) \xi(a, t-\tau)] \} d\tau. \end{aligned} \quad (10')$$

Next, we integrate the first term in (10) by parts with respect to x :

$$\begin{aligned} \int_a^b \lambda(x) x^{m-1} \frac{\partial u(x, \tau)}{\partial x} \frac{\partial \xi(x, t-\tau)}{\partial x} dx = & \lambda(b) b^{m-1} \frac{\partial u(b, \tau)}{\partial x} \xi(b, t-\tau) - \\ - \lambda(a) a^{m-1} \frac{\partial u(a, \tau)}{\partial x} \xi(a, t-\tau) - & \int_a^b \frac{\partial}{\partial x} \left[\lambda(x) x^{m-1} \frac{\partial u(x, \tau)}{\partial x} \right] \times \\ \times \xi(x, t-\tau) dx \end{aligned}$$

and on the basis of the convolution symmetry also establish that

$$\int_0^t u(x, \tau) \frac{\partial \xi(x, t-\tau)}{\partial \tau} d\tau = \int_0^t \frac{\partial u(x, \tau)}{\partial \tau} \xi(x, t-\tau) d\tau.$$

Then (10) takes the form

$$\begin{aligned} \delta J = & 2 \int_0^t \left\{ \int_a^b \left\{ \frac{1}{x^{m-1}} \left[\frac{\partial}{\partial x} \lambda(x) x^{m-1} \frac{\partial u(x, \tau)}{\partial x} \right] - c\rho(x) \frac{\partial u(x, \tau)}{\partial \tau} - \right. \right. \\ & \left. \left. - f(x, \tau) \right\} x^{m-1} \xi(x, t-\tau) dx + b^{m-1} \left[\lambda(b) \frac{\partial u(b, \tau)}{\partial x} + \right. \right. \end{aligned}$$

$$\begin{aligned}
& + \alpha_2 u(b, \tau) \Big] \zeta(b, t - \tau) + a^{m-1} \left[-\lambda(a) \frac{\partial u(a, \tau)}{\partial x} + \right. \\
& \left. + \alpha_1 u(a, \tau) \right] \zeta(a, t - \tau) \Big] d\tau.
\end{aligned} \tag{11}$$

Considering (11), we conclude that the function $u(x, \tau)$ satisfying the condition $\delta J = 0$ for $a < x < b$, $0 < \tau < t$ is a solution of the problem (1')-(4').

Following L. V. Kantorovich [2], we seek a solution of (1')-(4') in the first approximation in the form

$$u(x, \tau) = g(x) \psi(\tau), \tag{12}$$

where $g(x)$ is a known function of the coordinates that satisfies conditions (3')-(4'), while $\psi(\tau)$ is the desired unknown time function satisfying the condition $\psi(0) = 0$.

It is not difficult to show that for our problem in which $u(x, \tau)$ is determined in the form (12), the Euler equation (the condition for stationarity of the functional) will be

$$A\psi(t - \tau) - B\psi'(t - \tau) - C(t - \tau) = 0,$$

where

$$\begin{aligned}
A &= \int_a^b [\lambda(x) x^{m-1} g'(x)]' g(x) dx; \\
B &= \int_a^b c\rho(x) x^{m-1} g^2(x) dx; \\
C(\tau) &= \int_a^b f(x, \tau) g(x) x^{m-1} dx.
\end{aligned}$$

Thus in first approximation the solution of (1)-(4) will have the form

$$\begin{aligned}
T(x, \tau) &= g(x) \psi(\tau) + \varphi(x) + [T_{a_1}(\tau) - T_{a_1}(0)] \times \\
&\times \frac{(b-x)^2(2x+b-3a)}{(b-a)^3} + [T_{a_2}(\tau) - T_{a_2}(0)] \frac{(x-a)^2(3b-a-2x)}{(b-a)^3}.
\end{aligned}$$

The succeeding approximations are found in like manner.

To illustrate the application of the above, let us solve the one-dimensional symmetric problem of heat conduction when the initial temperature T_0 of the body and the ambient temperature T_a are constant for a body with constant thermophysical properties λ , c_p having no source (sink) $q_V(x, \tau)$. Here we assume initially that the temperature of the medium varies from T_0 to T_a over a small time interval $0 \leq \tau \leq \tau_0$, only then ($\tau_0 \leq \tau$) becoming constant:

$$T_a(\tau) = \begin{cases} \frac{T_0 - T_a}{\tau_0^2} (\tau - \tau_0)^2 + T_a, & 0 \leq \tau \leq \tau_0, \\ T_a, & \tau_0 \leq \tau. \end{cases}$$

Thus the congruence conditions (5), (6) are provided. Next we introduce the dimensionless coordinate $\eta = x/l_0$, the dimensionless time $\bar{\tau} = a\tau/l_0^2$ ($a = \lambda/c_p$), and the dimensionless intensity of heat transfer (the Biot number) $Bi = \alpha l_0/\lambda$ and assume that $T(\eta, \bar{\tau}) = u(\eta, \bar{\tau}) + T_a(\bar{\tau})$. Then our problem takes the form

$$\frac{1}{\eta^{m-1}} \frac{\partial}{\partial \eta} \left[\eta^{m-1} \frac{\partial u(\eta, \bar{\tau})}{\partial \eta} \right] = \frac{\partial u(\eta, \bar{\tau})}{\partial \bar{\tau}} + T_a'(\bar{\tau}), \tag{13}$$

$$-1 < \eta < 1, \quad \bar{\tau} > 0, \quad m = 1, 2, 3,$$

$$u(\eta, 0) = 0, \quad -1 < \eta < 1, \tag{14}$$

$$-\frac{\partial u(-1, \bar{\tau})}{\partial \eta} + Bi u(-1, \bar{\tau}) = 0, \quad \bar{\tau} > 0, \tag{15}$$

$$\frac{\partial u(1, \bar{\tau})}{\partial \eta} + Bi u(1, \bar{\tau}) = 0, \quad \bar{\tau} > 0. \tag{16}$$

It can be shown that solution of the given problem when

$$u(\eta, \bar{\tau}) = \left(\frac{2}{Bi} + 1 - \eta^2 \right) \psi(\bar{\tau})$$

is chosen as the first approximation is equivalent to solution of the following Euler equation:

$$\psi'(\bar{\tau}) + \mu_1 \psi(\bar{\tau}) = -\frac{\mu_1}{2m} T_a'(\bar{\tau}), \quad (17)$$

where

$$\mu_1 = \frac{m(m+4) \text{Bi}(\text{Bi}+m+2)}{2\text{Bi}+2(m+4) \text{Bi}+(m+2)(m+4)},$$

$$T_a'(\bar{\tau}) = \begin{cases} \frac{2(T_0 - T_a)}{\bar{\tau}_0^2} (\bar{\tau} - \bar{\tau}_0), & \bar{\tau} \leq \bar{\tau}_0, \\ 0, & \bar{\tau} > \bar{\tau}_0. \end{cases}$$

Solving (17), we obtain $\psi(\bar{\tau})$. We shall not give the computational relationships separately for $0 \leq \bar{\tau} \leq \bar{\tau}_0$ and $\bar{\tau}_0 \leq \bar{\tau}$ but shall just give the formula for Θ when $\bar{\tau}_0 \rightarrow 0$ (to permit comparison with the classical solutions, and owing to space limitations):

$$\Theta(\eta, \bar{\tau}) = \frac{T(\eta, \bar{\tau}) - T_a}{T_0 - T_a} = \frac{\mu_1}{2m} \left(\frac{2}{\text{Bi}} + 1 - \eta^2 \right) \exp(-\mu_1 \bar{\tau}). \quad (18)$$

Similarly, taking

$$u(\eta, \bar{\tau}) = \left(\frac{2}{\text{Bi}} + 1 - \eta^2 \right) \psi_1(\bar{\tau}) + \left(\frac{2}{\text{Bi}+2} + 1 - \eta^2 \right) \eta^2 \psi_2(\bar{\tau}),$$

for the second approximation, we obtain

$$\psi_1(\bar{\tau}) = \frac{m+6}{8} \frac{\text{Bi}}{\text{Bi}+2} \frac{D}{F} \frac{T_a - T_0}{\mu_2 - \mu_1} [(\mu_1 - \beta) \exp(-\mu_1 \bar{\tau}) - (\mu_2 - \beta) \exp(-\mu_2 \bar{\tau})], \quad (19)$$

$$\psi_2(\bar{\tau}) = \frac{(m+6)(m+8)}{8} \frac{\text{Bi}[\text{Bi}+2(m+4)]}{F} \frac{T_a - T_0}{\mu_2 - \mu_1} [\mu_1 \exp(-\mu_1 \bar{\tau}) - \mu_2 \exp(-\mu_2 \bar{\tau})]. \quad (20)$$

after carrying out the corresponding steps for $\bar{\tau}_0 \rightarrow 0$. In the formulas for $\psi(\bar{\tau})$,

$$D = (4-m) \text{Bi}^2 + 2(4-m)(m+6) \text{Bi} + 8(5m+22),$$

$$F = 3\text{Bi}^2 + 6(m+6) \text{Bi} + (m+6)(5m+22),$$

$$\beta = \frac{4(m+2)(m+8)(\text{Bi}+2)[\text{Bi}+2(m+4)]}{D},$$

$$\left. \begin{aligned} \mu_1 \\ \mu_2 \end{aligned} \right\} = \frac{(m+2)(m+6)}{F} \left\{ 2\text{Bi}^2 + 4(m+5) \text{Bi} + (m+4)(m+8) \mp \sqrt{[2\text{Bi}^2 + 4(m+5) \text{Bi} + (m+4)(m+8)]^2 - \frac{m(m+8)}{(m+2)(m+6)} \times \left[\frac{4(m+2)(m+8)(\text{Bi}+2)[\text{Bi}+2(m+4)]}{F} \right]} \right\}.$$

The quantities $\mu_1^{0.5}$ in the first and second approximations coincide exactly with the exact values of the first root of the characteristic equations of heat conduction tabulated in [3]. The second root of the characteristic equations given in [3] differs negligibly from $\mu_2^{0.5}$ (the discrepancy decreases from 6 to 0.1% as Bi decreases).

Analysis of the function $\Theta = \Theta(\eta, \tau)$ of the second approximation for monotonicity in the region $|\eta| \leq 0.5$ and comparative digital-computer calculations show that the approximate values Θ agree well with the exact values Θ_T for all Bi when

$$\tau > \frac{1}{\mu_2 - \mu_1} \left[\frac{3}{2} \ln \frac{\mu_2}{\mu_1} + \ln \frac{(M+N)\mu_2 - M\beta}{(M+N)\mu_1 - M\beta} \right],$$

where

$$M = \frac{\frac{2}{\text{Bi}} + 1 - \eta^2}{\text{Bi}+2} D; \quad N = (m+8)(\text{Bi}+2m+8) \left(\frac{2}{\text{Bi}+2} + 1 - \eta^2 \right) \eta^2.$$

In the region $|\eta| > 0.5$ a second-approximation error of less than 5% is observed beginning at $\bar{\tau} \geq 0.05$.

For the $Bi = Bi(\bar{\tau})$ case, which is of practical importance in thermophysics, if we use the above approach and symmetrize the smooth function $Bi(\bar{\tau})$ at the point $\bar{\tau}$ on the interval $[0, 2\bar{\tau}]$, as we did in [4], we obtain

$$u(\eta, \bar{\tau}) = - \left[\frac{2}{Bi(\bar{\tau}) + 1 - \eta^2} \right] \frac{m+4}{2} \exp \left[- \frac{m(m+4)}{2} \int_0^{\bar{\tau}} v(z) dz \right] \times \\ \times \int_0^{\bar{\tau}} v(\gamma) T'_a(\gamma) \exp \left[\frac{m+4}{2} \int_0^{\gamma} v(z) dz \right] d\gamma,$$

in the first approximation, where

$$v(z) = \frac{Bi(z) [Bi(z) + m + 2]}{2Bi^2(z) + 2(m+4)Bi(z) + (m+2)(m+4)}.$$

Problems of this sort have so far been solved only for certain $Bi = Bi(\bar{\tau})$ dependences [5].

To conclude we note that a separate paper will be devoted to analytic evaluation of the order of convergence and of the solution error for the approximate method used.

NOTATION

$\Theta = [T(x, \tau) - T_0] / [T_a - T_0]$ and $T(x, \tau)$, T_0 and T_a	are the dimensionless and dimensioned running temperatures, the initial temperature of the body, and the ambient temperature;
x and $\eta = x/l_0$, l_0	are the dimensioned and dimensionless coordinates of a point in the body and the characteristic length of the body;
τ and $\bar{\tau} = a\tau/l_0^2$	are the dimensioned and dimensionless time;
$a = \lambda/c_p$ and λ , c_p	are the thermal diffusivity and thermal conductivity, and the bulk specific heat;
$q_V(x, \tau)$	is the power of the bulk heat-evolution source;
α and $Bi = \alpha l_0/\lambda$	are the heat-transfer coefficient and the Biot number.

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